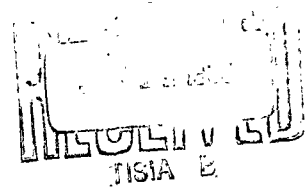


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EXAMINATION OF AN INVENTORY MODEL  
INCORPORATING PROBABILITIES OF OBSOLESCENCE

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EXAMINATION OF AN INVENTORY MODEL  
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1. Introduction and description of the models. This paper is devoted to the numerical study of two models of the inventory problem. The first model is called the ordinary model. The second is called the obsolescence model, and describes an extension of the ordinary model in which the items in the inventory may become obsolescence at any stage. "Obsolescence" will mean that the item in question is no longer to be used and the stock on hand is to be disposed of. It will be seen that the ordinary model is a special case of the obsolescence model.

The intention of this piece of work is the modest one of providing an explicit comparison, in one particular case, of optimal inventory policies with and without the presence of obsolescence probabilities. Additional numerical studies will lend further insight into our obsolescence model, but above all, analytic studies are needed.

In Section 2 we set up the recursion relation for the ordinary model, and specify numerically the constants and component cost functions. In Section 3 we do the corresponding work for the obsolescence model, introducing there a specific probability distribution of time of obsolescence. The solutions of the problems of finding the optimal policies and optimum total cost functions in these two models are presented in Section 4.

On both models the same number  $N$  of time periods is fixed ( $N$  will be taken as 5 in our numerical work). These periods will be designated as  $J_1, J_2, \dots, J_N$ , and the convention will be adopted that period  $N$  is the earliest in time, period  $N - 1$  the succeeding period and period 1 the last period. Thus, the pertinent time diagram is as follows, if we label the inventory points from  $N$  to 0 with increasing time:

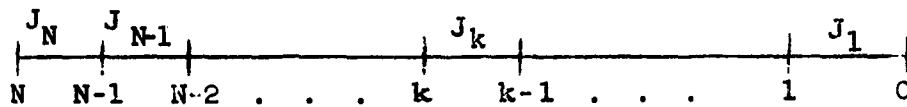


FIGURE I

The ordinary  $N$ -period model begins a period  $J_N$  with a primal stock of items in the inventory. Denote by  $x_N$  the size of the primal stock, which may be any real number in general but may be assumed to be nonnegative for this discussion. The primal stock can be increased by  $y_N - x_N$  units where  $y_N \geq x_N$ . The quantity of item in the inventory after ordering, namely  $y_N$ , is called the starting stock for period  $N$ . During period  $N$  there will be a demand for  $\xi_N$  units and it will be assumed that the demand, which may be zero, always occurs after any replenishment  $y_N - x_N$  to the primal stock  $x_N$ . For the following period,  $J_{N-1}$ , there will be a (possibly vanishing) left over stock from  $J_N$ , called the initial stock for period  $J_{N-1}$ , which will equal  $y_N - \xi_N$ , if this quantity is  $\geq 0$ . But this quantity may be negative, and

if so it will represent a shortage in the preceding period. If indeed  $y_N - \xi_N$  is negative, it will be assumed that any additional items obtained to replenish the initial stock in period  $J_{N-1}$  will first be consigned to the  $-(y_N - \xi_N)$  unfilled units of demand from the preceding period. The starting stock  $y_{N-1}$  for period  $J_{N-1}$  will be the initial stock  $y_N - \xi_N$  plus  $y_{N-1} - (y_N - \xi_N)$ , the amount by which the inventory is increased in period  $J_{N-1}$ . This procedure continues to period  $J_1$  where the initial stock is  $y_2 - \xi_2$ , the remainder from period 2 and where the starting stock  $y_1$  is initial stock  $y_2 - \xi_2$  plus  $y_1 - (y_2 - \xi_2)$ , the replenishment to the inventory. If items remain in the inventory after the demand in period 1, i.e., if  $y_1 - \xi_1 > 0$ , the remainder will be sold for salvage.

There are various costs associated with the models. The cost of ordering quantities of the item to augment the primal and starting stocks is called the ordering cost. For both the regular model and the obsolescence model the ordering cost will consist of the cost of the items ordered plus a cost for placing the order, the latter being called the setup cost. The cost of failing to have an inventory at a fixed period large enough to meet the demand of that period is called the penalty cost. The cost of having a surplus at the end of a period after the demand of that period is called the holding cost. These costs also appear in the same fashion in the ordinary and obsolescence models. Salvage cost, which is a negative cost, is, in the ordinary model, the value of the remaining items if any at the end of period 1. This definition of salvage cost for the ordinary model will be modified for the obsolescence model. Finally, there is a discount factor.

On both the ordinary and obsolescence models the demands in the successive periods are assumed to be independent and to be identically distributed according to a known probability distribution. Demand is nonnegative.

The obsolescence model for  $N$  periods begins initially like the ordinary model. The primal stock  $x_N$  is increased to the starting stock  $y_N$  and subsequently there is a nonnegative demand  $\xi_N$ . After the demand  $\xi_N$  in period  $J_N$  but before the beginning of period  $J_{N-1}$ , obsolescence may occur according to some known probability. When this occurs, any remaining items are sold for salvage and no further orders or demands occur--the process stops. If obsolescence does not occur, then at the beginning of period  $J_{N-1}$  the initial stock  $y_N - \xi_N$  is increased to the starting stock  $y_{N-1}$ . After the demand  $\xi_{N-1}$  in period  $J_{N-1}$  but before the beginning of period  $J_{N-2}$  obsolescence may occur with a certain probability. If obsolescence does occur here, then any remaining goods are sold for salvage. And so on, similarly.

It is clear from the above that salvage cost enters directly in each period in which the probability of obsolescence is not zero. When all probabilities of obsolescence are zero except for period 1, the obsolescence model becomes the ordinary model.

The component cost functions and the distribution of demand being known, the inventory problem is then to find an ordering policy for the  $N$  periods which will minimize the total expected discounted cost (but see Section 3). In the ordinary and obsolescence models the "optimal" policies are of the  $(s, S)$  type.

2. The recursion relation for the ordinary model. Let  $H_n$  denote the total discounted cost function for the  $n$ -period case,  $n = 1, 2, \dots$ . The total cost sustained will depend on the primal stock,  $x_n$ , the successive demands in the  $n$  periods,  $\xi_n, \xi_{n-1}, \dots, \xi_1$ , and the several starting stocks,  $y_n, y_{n-1}, \dots, y_1$ . (As usual, the "initial stock,"  $x_k$ , at  $t_k$  is the stock level resulting at the end of period  $J_{k+1}$ , before stock-replenishment at  $t_k$ , and the "starting stock,"  $a_{j_k}$ , at  $t_k$  is the stock level at the beginning of  $J_k$ , after stock-replenishment at  $t_k$ ; thus,  $y_k - x_k$  is the amount ordered for stock-replenishment at  $t_k$ .) Hence, the dependence of  $H_n$  is explicitly represented by  $H_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; y_n, y_{n-1}, \dots, y_1)$ .

If  $C$  denotes the replenishment cost function and  $l$  denotes the holding-shortage cost function--which two functions are the same for all periods--then evidently we have

$$(2.1) \quad H_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; y_n, y_{n-1}, \dots, y_1) = C(y_n - x_n) \\ + l(y_n - \xi_n) + \alpha H_{n-1}(y_n - \xi_n; \xi_{n-1}, \xi_{n-2}, \dots, \xi_1; y_{n-1}, \\ y_{n-2}, \dots, y_1)$$

for  $n = 2, 3, \dots$

where  $\alpha$  is the discount factor. For every period  $J_a$ ,  $k = 1, 2, \dots, n$ , the functions  $C$  and  $l$  are given by

$$(2.2) \quad C(z) = C_0 \cdot z + \begin{cases} K, & \text{if } z > 0 \\ 0, & \text{if } z = 0 \end{cases},$$

$$(2.3) \quad l(z) = \begin{cases} h \cdot z & \text{for } z \geq 0, \\ p \cdot (-z) & \text{for } z < 0, \end{cases}$$

where  $C_0$ ,  $h$  and  $p$  are constant unit costs, and  $K$  is the setup cost for ordering.

The function  $H_1$ , the total cost function for the temporally last period,  $J_1$ , is determined with the assumption of disposal of left over items for a specified salvage value. If  $w$  denotes the salvage gain function, then we have

$$(2.4) \quad H_1(x_1; \xi_1; y_1) = C(y_1 - x_1) + l(y_1 - \xi_1) - w(y_1 - \xi_1).$$

We take the function  $w$  to be characterized by a constant salvage value per unit of left over item, say  $w_0$ ; thus,  $w$  is given by

$$(2.5) \quad w(z) = \begin{cases} w_0 \cdot z, & z \geq 0, \\ 0, & z < 0. \end{cases}$$

Now (as usual) we consider the  $y_1, y_2, \dots, y_n$  in (2.1) replaced by functions  $Y_1(x_1), Y_2(x_2), \dots, Y_n(x_n)$  of the respective  $x_k$ , these functions to be determined according to an optimal principle, and thereby constituting the optimal policy. If we make this replacement, and for brevity set

$$(2.6) \quad \begin{aligned} y_n &= (Y_n, Y_{n-1}, \dots, Y_1), \\ H_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; y_n) &= H_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; Y_n(x_n), \\ &\quad Y_{n-1}(x_{n-1}), \dots, Y_1(x_1)), \end{aligned}$$

then from (2.1) we get--on regarding the  $\xi_k$  as random variables--

$$(2.7) \quad \begin{aligned} \mathcal{E} H_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; y_n) &= \mathcal{E} [C(Y_n(x_n)) - x_n] \\ &+ \mathcal{E} [1(Y_n(x_n) - \xi_n)] + \xi_n \\ &+ \alpha \mathcal{E} \left\{ \mathcal{E}^{\xi_n} [H_{n-1}(Y_n(x_n) - \xi_n; \xi_{n-1}, \xi_{n-2}, \dots, \xi_1; y_{n-1})] \right\}, \end{aligned}$$

where  $\mathcal{E}$  denotes expectation, and  $\mathcal{E}^{\xi_n}$  denotes conditional expectation given  $\xi_n$ .

The optimum principle is that (2.7) shall be minimized by suitable choice of  $y_n$ . If we denote this minimum by  $C_n(x_n)$ , then the customary argument gives, from (2.7),

$$(2.8) \quad C_n(x_n) = \min_{y \geq x_n} \left\{ \mathcal{E} [C(y - x_n)] + \mathcal{E} [1(y - \xi_n)] + \alpha \mathcal{E} [C_{n-1}(y - \xi_n)] \right\}$$

for  $n = 2, 3, \dots$

and the minimizing value of  $y$  in (2.8) is the value of the optimal component function  $Y_n(x_n)$ .

The determination of  $C_1(x_1)$  comes from (2.4); we find

$$(2.9) \quad C_1(x_1) = \min_{y \geq x_1} \left\{ \mathcal{E} [C(y - x_1)] + \mathcal{E} [1(y - \xi_1)] - \mathcal{E} [w(y - \xi_1)] \right\}.$$

Together, (2.8) and (2.9) enable us to determine, successively for  $n = 1, 2, \dots$ , the optimal component functions  $Y_k(x_k)$  and the optimal expected cost functions  $C_k(x_k)$ .

In our case at hand we are concerned with a five-period interval, and therefore we are interested in (2.9) and in (2.8) for  $n = 2, 3, 4$  and 5.



In the present numerical study we specialize to the following values for the constants characterizing our total cost function:

$$(2.10) \quad \left\{ \begin{array}{ll} C_0 = \text{replenishment cost per unit of item} & = \frac{5}{6} \\ K = \text{set-up cost for ordering} & = 1 \\ h = \text{holding cost per unit of item} & = \frac{1}{2} \\ p = \text{penalty cost per unit of item} & = 6 \\ w_0 = \text{salvage value per unit of item} & = \frac{1}{3} \\ \alpha = \text{discount factor} & = 1 \end{array} \right.$$

and we take the demands in the several periods to be independent and identically distributed, with density function  $\varphi$  given by

$$(2.11) \quad \varphi(\xi) = \begin{cases} e^{-\xi}, & \xi \geq 0 \\ 0, & \xi < 0. \end{cases}$$

We then have

$$(2.12) \quad \mathcal{E}[C(y - x)] = C(y - x) = \frac{5}{6} (y - x) + I_x(y)$$

where

$$(2.13) \quad I_x(y) = \begin{cases} 1 & \text{if } y > x \\ 0 & \text{if } y \leq x, \end{cases}$$

and

$$(2.14) \quad \mathcal{E}[1(y - \xi_k)] = \begin{cases} \frac{1}{2} \int_0^y (y - \xi) e^{-\xi} d\xi + 6 \int_y^\infty (\xi - y) e^{-\xi} d\xi, & y > 0, \\ 6 \int_0^\infty (\xi - y) e^{-\xi} d\xi, & y \leq 0 \end{cases}$$

$$= \begin{cases} \frac{1}{2} (-1 + y + 13e^{-y}), & y > 0, \\ 6(1 - y), & y \leq 0, \end{cases} \quad (\text{any } k)$$

and

$$(2.15) \quad \sum [C_{n-1}(y-\xi_n)] = \int_0^{\infty} C_{n-1}(y-\xi) e^{-\xi} d\xi,$$

and finally,

$$(2.16) \quad \begin{aligned} \mathcal{E}[w(y-\xi_1)] &= \begin{cases} \frac{1}{3} \int_0^y (y-\xi) e^{-\xi} d\xi, & y > 0, \\ 0, & y \leq 0, \end{cases} \\ &= \begin{cases} \frac{1}{3}(-1+y+e^{-y}), & y > 0, \\ 0, & y \leq 0. \end{cases} \end{aligned}$$

Inserting these evaluations into (2.9) we get

$$(2.17) \quad C_1(x) = \min_{y \geq x} \left[ \frac{5}{6} (y-x) + I_x(y) + \begin{cases} \frac{1}{6}(-1+y+37e^{-y}), & y > 0 \\ 6(1-y), & y \leq 0 \end{cases} \right]$$

and inserting them into (2.8) gives

$$(2.18) \quad \begin{aligned} C_n(x) = \min_{y \geq x} \left[ \frac{5}{6} (y-x) + I_x(y) + \begin{cases} \frac{1}{2}(-1+y+13e^{-y}), & y > 0, \\ 6(1-y), & y \leq 0 \end{cases} \right. \\ \left. + \int_0^{\infty} C_{n-1}(y-\xi) e^{-\xi} d\xi \right]. \end{aligned}$$

With (2.17) we may now determine the optimum policy component  $Y_1$  and the optimum expected cost function  $C_1$ . Then, iteratively, with (2.18) we determine  $Y_2, C_2, \dots, Y_5, C_5$ . By well-known arguments it follows that the optimum policy is an (3,8)-policy in each period. In Section 4 we give the results of our calculations, and we have there tabulated the optimal  $s_k$  and  $S_k$ ,  $k = 1, 2, \dots, 5$ .

3. The recursion relation for the obsolescence model. Let  $N$  denote the number of periods in which we are interested. This is specifically, in our present study, the number 5. For  $n = 1, 2, \dots, N$ , let  $\pi_n$  denote the probability that obsolescence occurs in the interval  $J_n$ . The latter eventualities are disjoint, by the nature of obsolescence. Furthermore since our inventory process comes to an end in any case after period  $J_1$ , we can consider the definition of obsolescence to be such that obsolescence certainly occurs in  $J_1$  if it does not occur before. (Or, equivalently, we may be given the datum that obsolescence, priorly defined, certainly occurs within  $N$  periods, and thereby  $N$  is defined.) Thus, we have

$$(3.1) \quad \sum_{n=1}^N \pi_n = 1.$$

Let  $\omega$  be a variable denoting the index of the period in which obsolescence occurs, For  $n = 1, 2, \dots, N$ , let  $\hat{H}_n$  denote the total discounted (to the inventory point  $n$ ) cost function for the periods  $J_n, J_{n-1}, \dots, J_1$ . This function depends on the variables described in Section 2, but as well on the variable  $\omega$ . And indeed the value of  $\hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; y_n, y_{n-1}, \dots, y_1; \omega)$  is determined by the values of  $x_n, \xi_n, \xi_{n-1}, \dots, \xi_\omega, y_n, y_{n-1}, \dots, y_\omega$  only.

The functions  $C, l$  and  $w$ , and the discount factor  $\alpha$  are the same as in the ordinary model. Recalling that when obsolescence occurs in a particular period, any left-over quantity of the item is sold for salvage, we see that in the present case the relation between  $\hat{H}_n$  and  $\hat{H}_{n-1}$  is of the following form:

$$(3.2) \quad \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; y_n, y_{n-1}, \dots, y_1; \omega) =$$

$$= \begin{cases} 0, & \text{if } \omega > n, \\ c(y_n - x_n) + l(y_n - \xi_n) + \begin{cases} -w(y_n - \xi_n), & \text{if } \omega = n, \\ \alpha \hat{H}_{n-1}(y_n - \xi_n; \xi_{n-1}, \xi_{n-2}, \dots, \xi_1; y_{n-1}, y_{n-2}, \dots, y_1; \omega), & \text{if } \omega \leq n-1. \end{cases} \end{cases}$$

for  $n = 2, 3, \dots, N$

For  $n = 1$ , we have simply:

$$(3.3) \quad \hat{H}_1(x_1; \xi_1; y_1; \omega) = \begin{cases} 0, & \text{if } \omega > 1, \\ c(y_1 - x_1) + l(y_1 - \xi_1) - w(y_1 - \xi_1), & \text{if } \omega = 1. \end{cases}$$

Let us denote the policy functions--to be determined by an optimality principle--by  $\hat{Y}_1(x_1), \hat{Y}_2(x_2), \dots, \hat{Y}_N(x_N)$ , and set

$$(3.4) \quad \begin{cases} \hat{Y}_n = (\hat{Y}_n, \hat{Y}_{n-1}, \dots, \hat{Y}_1), \\ \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{Y}_n; \omega) = \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{Y}_n(x_n), \hat{Y}_{n-1}(x_{n-1}), \dots, \hat{Y}_1(x_1); \omega). \end{cases}$$

Now, for the present model the question presents itself whether the optimization principle should be to minimize, as is usual, the expectation

$$(3.5) \quad E \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{Y}_n; \omega)$$

for  $n = 1, 2, \dots, N$ , or alternatively, to minimize the conditional expectation

$$(3.6) \quad \mathcal{E} \left[ \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{y}_n; \omega) \mid \omega \leq n \right]$$

for each  $n$ . On general grounds the latter principle seems the more pertinent, the argument being that optimality considerations for the periods  $J_n, J_{n-1}, \dots, J_1$  ought not to give any positive weighting to eventualities which, because they entail obsolescence before the period  $J_n$ , involve no behavior within the periods  $J_n, J_{n-1}, \dots, J_1$ . But in fact, in our specific model there is no difference between the two principles. This is so because the obsolescence probabilities  $\pi_k$  are fixed and the quantities which would get positive weighting under the first principle and not under the second are in fact all 0, so that the weighting is irrelevant. To see this more precisely, notice that by (3.2) and (3.3) we have, for all  $n = 1, 2, \dots, N$ , that  $\hat{H}_n = 0$  for  $\omega > n$ , and therefore (looking on the  $\xi_k$  and  $\omega$  as random variables)

$$\begin{aligned} (3.7) \quad \mathcal{E} \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{y}_n; \omega) &= \sum_{r=1}^N \pi_r \mathcal{E} \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{y}_n; r) \\ &= \sum_{r=1}^n \pi_r \mathcal{E} \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{y}_n; r) \\ &= \left( \sum_{k=1}^n \pi_k \right) \cdot \sum_{r=1}^n \frac{\pi_r}{\left( \sum_{k=1}^n \pi_k \right)} \mathcal{E} \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{y}_n; r) \\ &= \left( \sum_{k=1}^n \pi_k \right) \mathcal{E} \left[ \hat{H}_n(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{y}_n; \omega \mid \omega \leq n) \right] \end{aligned}$$

for  $n = 1, 2, \dots, N$ .

Thus, for each  $n$ , the expressions (3.5) and (3.6) differ only by a constant factor, and therefore the minimization of one is equivalent to the minimization of the other. (We are, of course, tacitly assuming in all our deliberations here that the  $\pi_k$  are suitably nonvanishing.)

Replacing the  $y_k$  by  $\hat{Y}_k(x_k)$  in (3.2) and taking expectations, we get

$$\begin{aligned}
 (3.8) \quad \mathcal{E}^{\hat{H}_n}(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{\mathcal{J}}_n; \omega) &= \left( \sum_{k=1}^n \pi_k \right) \left\{ C(\hat{Y}_n(x_n) - x_n) \right. \\
 &\quad \left. + \mathcal{E} [1(\hat{Y}_n(x_n) - \xi_n)] \right\} \\
 &\quad - \pi_n \mathcal{E} [\omega(\hat{Y}_n(x_n) - \xi_n)] \\
 &\quad + \alpha \sum_{r=1}^{n-1} \pi_r \mathcal{E}^{\hat{H}_{n-1}}(\hat{Y}_n(x_n) - \xi_n; \xi_{n-1}, \xi_{n-2}, \dots, \xi_1; \hat{\mathcal{J}}_{n-1}; r), \\
 &\quad \underline{n = 2, 3, \dots, N.}
 \end{aligned}$$

This relation takes on a much more convenient form when expressed in terms of the conditional expectations (3.6). For brevity, let  $\mathcal{E}^{(n)}$  denote the conditional expectation operator given  $\omega \leq n$ . Then, on dividing (3.8) through by  $(\sum_{k=1}^n \pi_k)$  and utilizing (3.7)--both as it stands and with  $n$  replaced by  $n - 1$ --we find that (3.8) is equivalently expressed as:

$$\begin{aligned}
 (3.9) \quad \mathcal{E}^{(n)\hat{H}_n}(x_n; \xi_n, \xi_{n-1}, \dots, \xi_1; \hat{\mathcal{J}}_n; \omega) &= C(\hat{Y}_n(x_n) - x_n) \\
 &\quad + \mathcal{E} [1(\hat{Y}_n(x_n) - \xi_n)] - \mu_n \mathcal{E} [\omega(\hat{Y}_n(x_n) - \xi_n)] \\
 &\quad + \alpha(1 - \mu_n) \mathcal{E}^{(n-1)\hat{H}_{n-1}}(\hat{Y}_n(x_n) - \xi_n; \xi_{n-1}, \xi_{n-2}, \\
 &\quad \dots, \xi_1; \hat{\mathcal{J}}_{n-1}; \omega), \\
 &\quad \underline{\text{for } n = 2, 3, \dots, N,}
 \end{aligned}$$

where

$$(3.10) \quad \mu_n \stackrel{\text{def}}{=} \frac{\pi_n}{\sum_{k=1}^n \pi_k}.$$

Then, if  $\hat{C}_n(x_n)$  denotes the minimum of (3.9), we have:

$$(3.11) \quad \hat{C}_n(x) = \min_{y \geq x} \left\{ C(y-x) + \mathcal{E}[1(y-\xi_n)] - \mu_n \mathcal{E}[w(y-\xi_n)] \right. \\ \left. + \alpha(1-\mu_n) \mathcal{E} \hat{C}_{n-1}(y-\xi_n) \right\}$$

for  $n = 2, 3, \dots, N$ .

For  $n = 1$ , we obtain

$$(3.12) \quad \hat{C}_1(x) = \min_{y \geq x} \left\{ C(y-x) + \mathcal{E}[1(y-\xi_1)] - \mathcal{E}[w(y-\xi_1)] \right\}.$$

For each  $n$ , the minimizing  $y$  for a given  $x$  is the optimal policy value  $\hat{Y}_n(x)$ .

Substituting into (3.11) and (3.12) the detailed functions and constants as specified in Section 2, we get:

$$(3.13) \quad \hat{C}_1(x) = \min_{y \geq x} \left[ \frac{5}{6}(y-x) + I_x(y) + \begin{cases} \frac{1}{6}(-1+y+37e^{-y}), & y > 0 \\ 6(1-y), & y \leq 0 \end{cases} \right]$$

(notice that  $\hat{C}_1$  is identical with  $C_1$ , given in (2.17)), and

$$(3.14) \quad \hat{C}_n(x) = \min_{y \geq x} \left[ \frac{5}{6}(y-x) + I_x(y) + \begin{cases} \frac{1}{2}(-1+y+13e^{-y}) - \frac{\mu_n}{3}(-1+y+e^{-y}), & y > 0 \\ 6(1-y), & y \leq 0 \end{cases} \right. \\ \left. + (1-\mu_n) \int_0^\infty \hat{C}_{n-1}(y-\xi) e^{-\xi} d\xi \right].$$

We see that the form of the problem here is the same as in the case of the ordinary model, there being simply the changes in coefficients in the recursion relation (3.14) due to the  $\mu_n$ . Again the optimal policy is of the  $(s, S)$ -type for each period, and in Section 4 we present the optimal  $s_k$  and  $S_k$ .

We shall carry out our numerical study for the set of values of the  $\pi_k$  as tabulated below; we tabulate also the  $\mu_k$  and the quantities

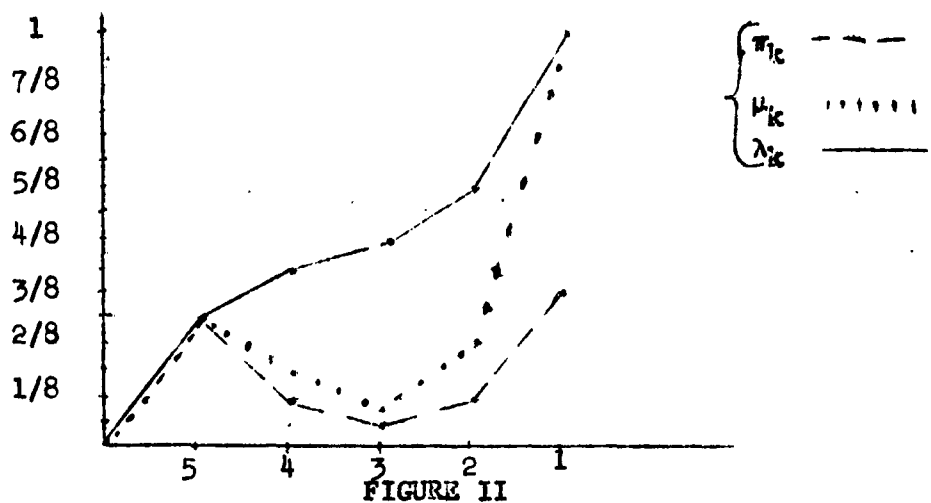
$$(3.15) \quad \lambda_k \stackrel{\text{def}}{=} \sum_{n=k}^5 \pi_n = \text{probability that obsolescence occurs in one of the periods } J_5, J_4, \dots, J_k.$$

TABLE I

k	$\pi_k$	$\mu_k$	$\lambda_k$
1	$\frac{3}{8}$	1	1
2	$\frac{1}{8}$	$\frac{1}{4}$	$\frac{5}{8}$
3	$\frac{1}{16}$	$\frac{1}{9}$	$\frac{1}{2}$
4	$\frac{1}{8}$	$\frac{2}{11}$	$\frac{7}{16}$
5	$\frac{5}{16}$	$\frac{5}{16}$	$\frac{5}{16}$

graphically, these quantities look as follows:





4. The computational results. The results of carrying out the minimizations in (2.17), (2.18) and in (3.13), (3.14) are the following:

ORDINARY MODEL

$$(s_1, s_1) = (0.67295, 1.81915)$$

$$c_1(x) = \begin{cases} 3.65249 - \frac{5}{6}x & x < 0.67295 \\ -\frac{1}{6} + \frac{1}{6}x + \frac{1}{6}e^{-x} & x \geq 0.67295 \end{cases}$$

$$(s_2, s_2) = (1.36731, 2.61030)$$

$$c_2(x) = \begin{cases} 6.03523 - \frac{5}{6}x & x < 1.36731 \\ -\frac{5}{6} + \frac{2}{3}x + 10.47669 e^{-x} - \frac{1}{6}xe^{-x} & x \geq 1.36731 \end{cases}$$

$$(s_3, S_3) = (1.52891, 3.06648)$$

$$8.52142 - \frac{5}{6}x \quad x < 1.52891$$

$$C_3(x) = \begin{aligned} & -2 + \frac{7}{6}x + 11.20586 e^{-x} + 10.47669 e^{-x}x \\ & + 3.08333 e^{-x}x^2 \quad x \geq 1.52891 \end{aligned}$$

$$(s_4, S_4) = (1.51388, 3.34470)$$

$$11.04205 - \frac{5}{6}x \quad x < 1.51388$$

$$C_4(x) = \begin{aligned} & 8.85475 - \frac{1}{3}x + 6\frac{1}{2} e^{-x} \quad 1.51388 \leq x < 1.52891 \\ & -\frac{2}{3} + \frac{1}{3}x + 17.10608 e^{-x} + 11.20586 e^{-x}x \\ & + 5.23834 e^{-x}x^2 + 1.02776 e^{-x}x^3 \\ & 1.52891 \leq x \end{aligned}$$

$$(s_5, S_5) = (1.42970, 3.77837)$$

$$13.64619 - \frac{5}{6}x \quad x < 1.42970$$

$$11.37537 - \frac{1}{3}x + 6\frac{1}{2} e^{-x} \quad 1.42970 \leq x < 1.5.388$$

$$C_5(x) = \begin{aligned} & 8.68808 + \frac{1}{6}x + 5.4319 e^{-x} \\ & + 6\frac{1}{2} e^{-x}x \quad 1.51388 \leq x < 1.52891 \\ & - 5\frac{5}{6} + 2\frac{1}{6}x \quad 21.35778 e^{-x} + 17.10608 e^{-x}x \\ & + 5.60293 e^{-x}x^2 + 1.74609 e^{-x}x^3 \\ & + 0.25694 e^{-x}x^4 \quad 1.52891 \leq x \end{aligned}$$

OBSOLESCENCE MODEL

$$(\hat{s}_1, \hat{s}_1) = (0.67295, 1.81915)$$

$$\hat{C}_1(x) = \begin{aligned} & 3.65249 - \frac{5}{6}x & x < 0.67295 \\ & -\frac{1}{6} + \frac{1}{5}x + \frac{1}{6}e^{-x} & x \geq 0.67295 \end{aligned}$$

$$(\hat{s}_2, \hat{s}_2) = (1.19718, 2.4649)$$

$$\hat{C}_2(x) = \begin{aligned} & 5.49071 - \frac{5}{6}x & x < 1.19718 \\ & -\frac{2}{3} + \frac{13}{24}x + 9.39913 e^{-x} + 4.625 e^{-x}x & x \geq 1.19718 \end{aligned}$$

$$(\hat{s}_3, \hat{s}_3) = (1.4024, 2.8852)$$

$$\hat{C}_3(x) = \begin{aligned} & 7.49881 - \frac{5}{6}x & x < 1.4024 \\ & -1.53702 + 0.94443x + 10.83690 e^{-x} \\ & \quad + 8.35474 e^{-x}x + 2.05553 e^{-x}x^2 & x \geq 1.4024 \end{aligned}$$

$$(\hat{s}_4, \hat{s}_4) = (1.26515, 3.0228)$$

$$\hat{C}_4(x) = \begin{aligned} & 8.94219 - \frac{5}{6}x & x < 1.26515 \\ & 6.37780 - 0.24270x + 6.43936 e^{-x} \\ & 1.26515 \leq x < 1.4024 \\ & -2.46966 + 1.21183x + 13.40940 e^{-x} \\ & \quad + 8.86653 e^{-x}x + 3.41784 e^{-x}x^2 \\ & \quad + 0.56059 e^{-x}x^3 & x \geq 1.4024 \end{aligned}$$

$$(\hat{s}_5, \hat{S}_5) = (1.11243, 2.82610)$$

$$9.15756 - \frac{5}{6}x \quad x < 1.11243$$

$$6.3284 + 0.65624x + 6.39585 e^{-x} \quad 1.11243 \leq x < 1.26515$$

$$\begin{aligned} \hat{C}_5(x) = & 4.15577 + 1.062304 + 6.66088e^{-x} \\ & + 4.42706 e^{-x}x \quad 1.26515 \leq x < 1.4024 \\ & -2.92635 + 2.06232x + 14.50318 e^{-x} \\ & + 9.21896 e^{-x}x + 3.04787e^{-x}x^2 \quad x > 1.4024 \\ & + 0.78525 e^{-x}x^3 + 0.09635 e^{-x}x^4 \end{aligned}$$

We summarize the critical numbers in the following table and graph:

TABLE II

k	Ordinary Model		Obsolescence Model	
1	0.67295	1.81915	0.67295	1.81915
2	1.36731	2.61030	1.19718	2.46490
3	1.52891	3.06648	1.40240	2.88520
4	1.51388	3.34470	1.26515	3.02280
5	1.42970	3.77837	1.11243	2.82610

NOTATION

1) Ordinary model

$s_k$ : —————

$s_k$ : - - - - -

2) Obsolescence model

$\hat{s}_k$ : .....  
 $\hat{s}_k$ : x x x x

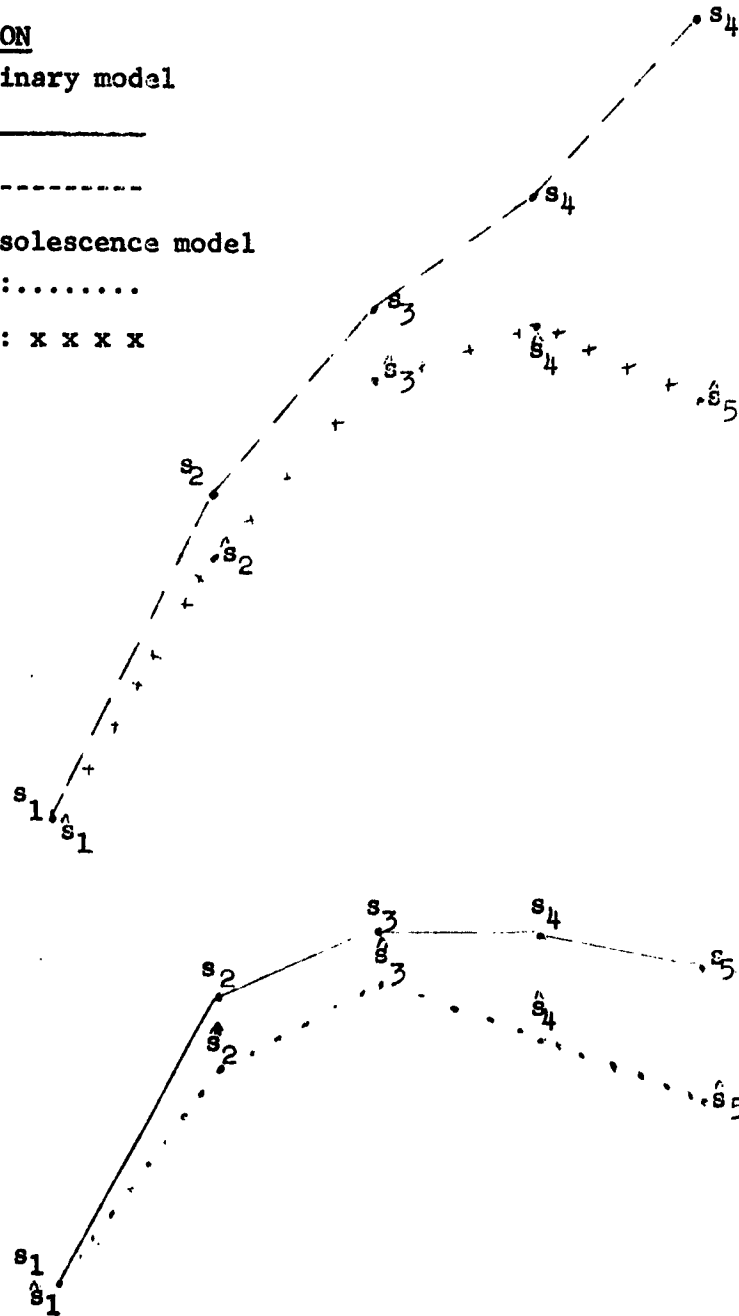


FIGURE III

The domination of  $\hat{S}_k$  by  $S_k$  and  $\hat{s}_k$  by  $s_k$  for  $k = 2, 3, 4, 5$  reflect the possibility of termination of the obsolescence model before period 1 and hence the need for smaller inventories. The agreement of the costs functions  $C_1(x)$  and  $\hat{C}_1(x)$  was noted in (3.13) and is the reason for the agreement of  $\hat{S}_1$  with  $S_1$  and of  $\hat{s}_1$  with  $s_1$ . The concave properties of the  $s_k$ -curve and the  $\hat{s}_k$ -curve are a consequence of the fact the ordering cost function  $C(\cdot)$  is not convex (see (2.2)). The concavity of the  $\hat{S}_k$ -curve is reflected in part by the relatively high conditional probability of obsolescence in period 5 (see Table I).

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